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ventional control theory), modern control theory, and robust control theory. This book presents comprehensive treatments of the analysis and design of control systems based on the classical control theory and modern control theory. A brief introduction of robust control theory is included in Chapter 10.

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24. CHAPTER 2. E2.4. Mathematical Models of Systems. Since $R(s) = 1/s$, we have. $Y(s) = 6(s + 50) / (s(s + 30)(s + 10))$ The partial fraction expansion of $Y(s)$ is given by $A_1/A_2/A_3$ $Y(s) = + + s s ...$

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With modern computer control systems, scaling for unit conversions is becoming more common in the controller signal path. Sometimes a display has been scaled but the signal in the loop path has not. You must pay attention to this detail and make sure you are using the correct units in your computations. There is more discussion in this article.

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